

# Laman graphs are generically bearing rigid in arbitrary dimensions

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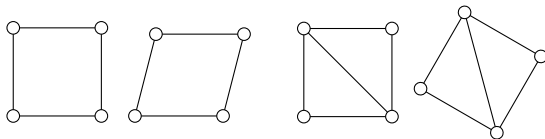
<sup>4</sup>Gwangju Institute of Science and Technology, Korea

December 2017

# What is bearing rigidity?

Revisit distance rigidity:

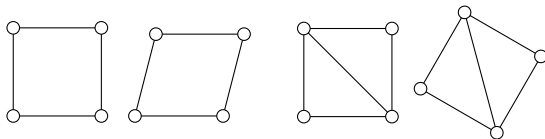
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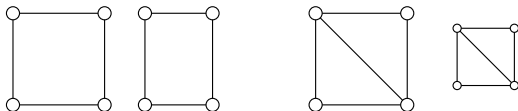
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Bearing rigidity:

◇ If we fix the bearing of each edge in a network, can the geometric pattern of the network be uniquely determined?



Loose definition: a network bearing rigid if its bearings can uniquely determine its geometric pattern.

## Why study bearing rigidity?

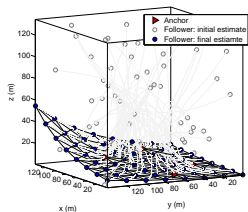
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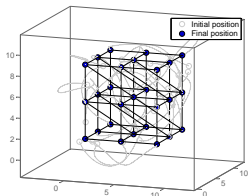
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- ◇ In recent years: Formation control and network localization [Eren et al., 2003, Bishop, 2011, Eren, 2012, Zelazo et al., 2014, Zhao and Zelazo, 2016a]

# Why study bearing rigidity?

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- ◇ In recent years: Formation control and network localization [Eren et al., 2003, Bishop, 2011, Eren, 2012, Zelazo et al., 2014, Zhao and Zelazo, 2016a]
- ◇ Network localization:



- ◇ Formation control:



## Two key problems in bearing rigidity theory

- How to determine the bearing rigidity of a given network?
- How to construct a bearing rigid network from scratch?

◇ Notations:

- Graph:  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$  where  $\mathcal{V} = \{1, \dots, n\}$  and  $\mathcal{E} \subseteq \mathcal{V} \times \mathcal{V}$
- Configuration:  $p_i \in \mathbb{R}^d$  with  $i \in \mathcal{V}$  and  $p = [p_1^T, \dots, p_n^T]^T$ .
- Network: graph+configuration



## Notations for Bearing Rigidity

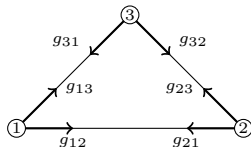
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◇ Bearing:

$$g_{ij} = \frac{p_j - p_i}{\|p_j - p_i\|} \quad \forall (i, j) \in \mathcal{E}.$$

Example:



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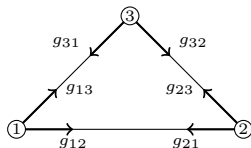
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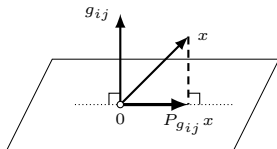


◇ An orthogonal projection matrix:

$$P_{g_{ij}} = I_d - g_{ij}g_{ij}^T,$$

# Notations for Bearing Rigidity

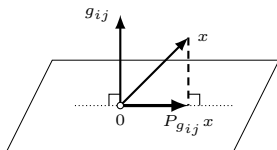
◇ Properties:



- $P_{g_{ij}}$  is symmetric positive semi-definite and  $P_{g_{ij}}^2 = P_{g_{ij}}$
- $\text{Null}(P_{g_{ij}}) = \text{span}\{g_{ij}\} \iff P_{g_{ij}} x = 0$  iff  $x \parallel g_{ij}$  (important)

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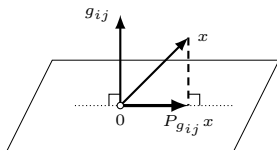


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$$[\mathcal{B}]_{ij} = \begin{cases} \mathbf{0}_{d \times d}, & i \neq j, (i, j) \notin \mathcal{E} \\ -P_{g_{ij}}, & i \neq j, (i, j) \in \mathcal{E} \\ \sum_{j \in \mathcal{N}_i} P_{g_{ij}}, & i \in \mathcal{V} \end{cases}$$

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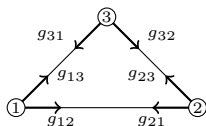


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Example:



$$\mathcal{B} = \begin{bmatrix} P_{g_{12}} + P_{g_{13}} & -P_{g_{12}} & -P_{g_{13}} \\ -P_{g_{21}} & P_{g_{21}} + P_{g_{23}} & -P_{g_{23}} \\ -P_{g_{31}} & -P_{g_{32}} & P_{g_{31}} + P_{g_{32}} \end{bmatrix}$$

# Examine the bearing rigidity of a given network

Condition for Bearing Rigidity [Zhao and Zelazo, 2016b]

A network is bearing rigid if and only if  $\text{rank}(\mathcal{B}) = dn - d - 1$

Proof.

$$f(p) \triangleq \begin{bmatrix} g_1 \\ \vdots \\ g_m \end{bmatrix} \in \mathbb{R}^{dm}.$$

$$R(p) \triangleq \frac{\partial f(p)}{\partial p} \in \mathbb{R}^{dm \times dn}.$$

$$df(p) = R(p)dp$$

Trivial motions: translation and scaling



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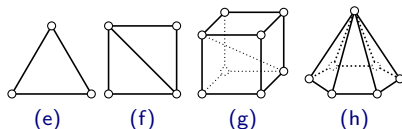
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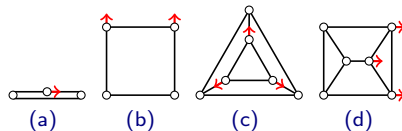
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◇ Examples of bearing rigid networks:



◇ Examples of networks that are not bearing rigid:

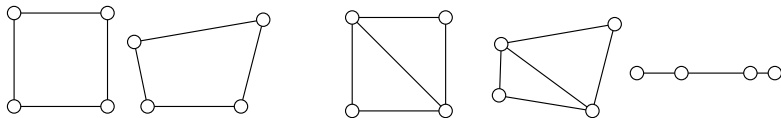


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- ◇ Need to design graph  $\mathcal{G}$  and configuration  $p$



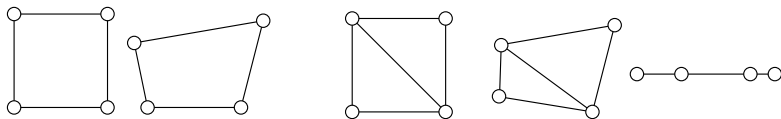
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- ◇ Need to design graph  $\mathcal{G}$  and configuration  $p$
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- ◇ Intuitively, it seems configuration is not that important. Is it true?

### Definition (**Generically Bearing Rigid Graphs**)

A graph  $\mathcal{G}$  is generically bearing rigid in  $\mathbb{R}^d$  if there exists at least one configuration  $p$  in  $\mathbb{R}^d$  such that  $(\mathcal{G}, p)$  is bearing rigid.

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## Lemma (Density of General Bearing Rigid Graphs)

*If  $\mathcal{G}$  is generically bearing rigid in  $\mathbb{R}^d$ , then  $(\mathcal{G}, p)$  is bearing rigid for almost all  $p$  in  $\mathbb{R}^d$  in the sense that the set of  $p$  where  $(\mathcal{G}, p)$  is not bearing rigid is of measure zero. Moreover, for any configuration  $p_0$  and any small constant  $\epsilon > 0$ , there always exists a configuration  $p$  such that  $(\mathcal{G}, p)$  is bearing rigid and  $\|p - p_0\| < \epsilon$ .*

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Summary:

- If a graph is generically bearing rigid, then for any almost all configurations the corresponding network is bearing rigid.
- If a graph is not generically bearing rigid, by definition for any configuration the corresponding network is not bearing rigid.

## Construction of bearing rigid graphs

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A graph  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$  is Laman if  $|\mathcal{E}| = 2|\mathcal{V}| - 3$  and every subset of  $k \geq 2$  vertices spans at most  $2k - 3$  edges.

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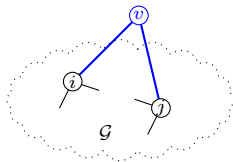
### Definition (Henneberg Construction)

Given a graph  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ , a new graph  $\mathcal{G}' = (\mathcal{V}', \mathcal{E}')$  is formed by adding a new vertex  $v$  to  $\mathcal{G}$  and performing one of the following two operations:

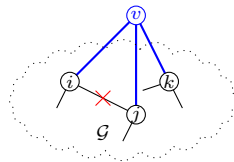
- Vertex addition:* connect vertex  $v$  to any two existing vertices  $i, j \in \mathcal{V}$ . In this case,  $\mathcal{V}' = \mathcal{V} \cup \{v\}$  and  $\mathcal{E}' = \mathcal{E} \cup \{(v, i), (v, j)\}$ .
- Edge splitting:* consider three vertices  $i, j, k \in \mathcal{V}$  with  $(i, j) \in \mathcal{E}$  and connect vertex  $v$  to  $i, j, k$  and delete  $(i, j)$ . In this case,  $\mathcal{V}' = \mathcal{V} \cup \{v\}$  and  $\mathcal{E}' = \mathcal{E} \cup \{(v, i), (v, j), (v, k)\} \setminus \{(i, j)\}$ .

# Construction of bearing rigid graphs

Two operations in Henneberg construction:



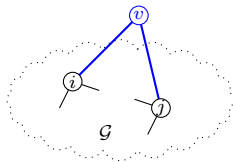
(a) Vertex addition



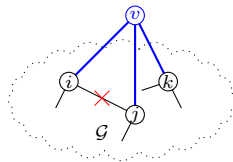
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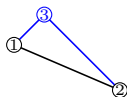


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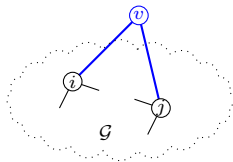
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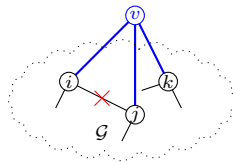
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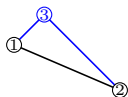


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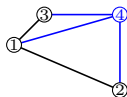


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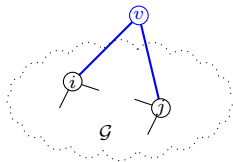
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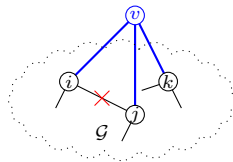
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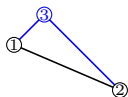


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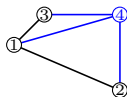


(b) Edge splitting

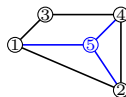
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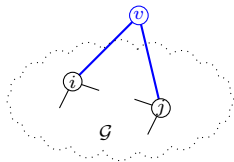
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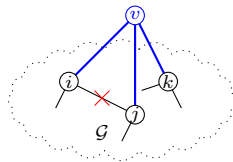
Step 3: edge splitting

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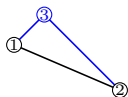


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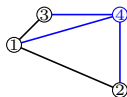


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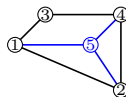
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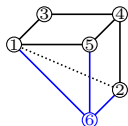
Step 1: vertex addition



Step 2: edge splitting



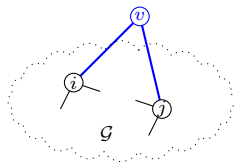
Step 3: edge splitting



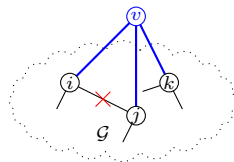
Step 4: edge splitting

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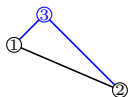


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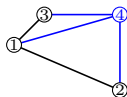


(b) Edge splitting

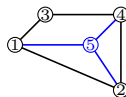
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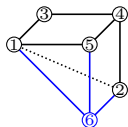
Step 1: vertex addition



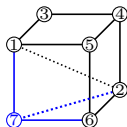
Step 2: edge splitting



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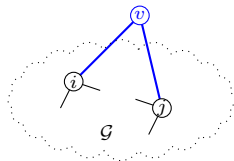
Step 4: edge splitting



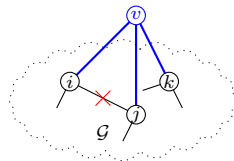
Step 5: edge splitting

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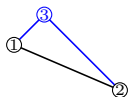


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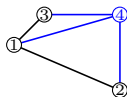


(b) Edge splitting

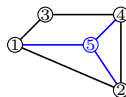
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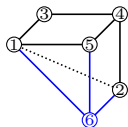
Step 1: vertex addition



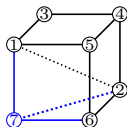
Step 2: edge splitting



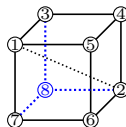
Step 3: edge splitting



Step 4: edge splitting



Step 5: edge splitting



Step 6: edge splitting



## Theorem (Main Result)

*Laman graphs are generically bearing rigid in arbitrary dimensions.*

◇ Rephrase the main result: If a graph is Laman, then for almost all configurations the corresponding network is bearing rigid.

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## Proof.

Partition  $\mathcal{B}$  into

$$\mathcal{B} = \begin{bmatrix} \mathcal{B}_{11} & \mathcal{B}_{12} \\ \mathcal{B}_{21} & \mathcal{B}_{22} \end{bmatrix},$$

where  $\mathcal{B}_{22} \in \mathbb{R}^{2d \times 2d}$  corresponds to nodes  $i, j$ . Then  $\mathcal{B}'$  can be expressed as

$$\mathcal{B}' = \left[ \begin{array}{cc|c} \mathcal{B}_{11} & \mathcal{B}_{12} & 0 \\ \mathcal{B}_{21} & \mathcal{B}_{22} + D & F \\ \hline 0 & F^T & E \end{array} \right],$$



- ◇ Question: is Laman both necessary and sufficient for bearing rigidity?

## Construction of bearing rigid graphs

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- ◇ Yes, in  $\mathbb{R}^2$

### Theorem

*A graph is bearing rigid in  $\mathbb{R}^2$  if and only if the graph contains a Laman spanning subgraph.*

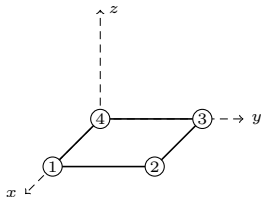
# Construction of bearing rigid graphs

- ◇ Question: is Laman both necessary and sufficient for bearing rigidity?
- ◇ Yes, in  $\mathbb{R}^2$

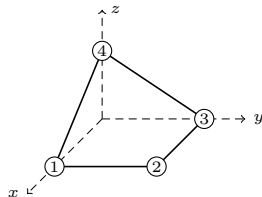
## Theorem

*A graph is bearing rigid in  $\mathbb{R}^2$  if and only if the graph contains a Laman spanning subgraph.*

- ◇ No, in higher dimensions



(a)



(b)

- ◇ Two key problems in the bearing rigidity theory:
  - How to examine the bearing rigidity of a given network?
    - Bearing Laplacian
    - Rank condition
  - How to construct a bearing rigid network?
    - Graph is critical
    - Laman graphs are generically bearing rigid

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